**Introduction**

One key area where machine learning can be applied in the aerospace sector is through the use of augmented reality. Machine learning models can be used to make AR modules more efficient and accurate, allowing users to gain better insights while performing a variety of tasks, such as maintenance, assembly, and design.

The following report details the process for developing a machine learning model to predict the corresponding maintenance step for a part, given a set of X, Y, and Z coordinates. The data is organized into 4 columns, 3 for each of the coordinate axes, which are the features, and 1 for the maintenance step, which will be the label, or target. There are a total of 13 unique maintenance steps. This is an example of a supervised learning, multi-classification problem.

**Data Visualization**

Before any effort is made to train a model, it is first necessary to gain an understanding of the raw data. This was accomplished by loading the data contained in a .csv file into a pandas dataframe for effective manipulation and analysis.

Une image contenant texte, Police, capture d’écran

Description générée automatiquementThe first thing to note is the integrity of the data. From the figure below, it can be seen that there are no missing or null values, and as such imputation will not be required.

Figure 1: Results of the df.info() method on the raw data

Next, a simple statistical summary was performed and is summarized below.

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Description générée automatiquement

Figure 2: Results of the df.describe() method on the data

From figure 2, the most

Une image contenant capture d’écran, texte, Tracé, ligne

Description générée automatiquementThe following figure presents the distribution of the classes in the data.

Figure 3: Distribution of each step in the dataset

From figure 3, is it is readily apparent that steps 7, 8, and 9 occur far more frequently in the data than the others, which are all represented equally. This could imply that these steps are more complicated, and have many fine adjustments associated with them.

At this point, the raw data was understood enough to create separate train and test sets. To do this, stratified sampling was utilized to maintain the distribution of steps shown in figure 3.

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Description générée automatiquementUne image contenant diagramme, capture d’écran, Tracé, ligne

Description générée automatiquementFurther exploration was conducted using the separated training set. Presented next are the boxplots of each coordinate, as well as their distribution.

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Description générée automatiquementUne image contenant texte, capture d’écran, Rectangle, ligne

Description générée automatiquementFigure 4: X-coordinate boxplot Figure : X-coordinate distribution

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Description générée automatiquementUne image contenant diagramme, ligne, Plan, Rectangle

Description générée automatiquementFigure 5: Y-coordinate boxplot Figure: Y-coordinate distribution

Figure 6: Z-coordinate boxplot Figure: Z-coordinate distribution

From figures 4,6, and 8, a few interesting observations can be made. Firstly, for each step, the range of the X and Y coordinates is very small, often 0. By contrast, there exists more “movement” the Z axis, especially for steps 7, 8, and 9. This could imply poor correlation between the Z-coordinate and the corresponding step, as there is a wide range of possibilities for each step. This will be confirmed in the correlation analysis in the proceeding section.

Secondly, the scale of the different axis differ. For example, the X-values range from about 0 to 9, whereas the Z-values only from 0 to 2.5. Due to these differences, scaling of the features will be required. The decision to use a StandardScaler or a MinMax scaler will be in a future section on data preprocessing.

**Correlation Analysis**

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Description générée automatiquementTo perform the correlation analysis, the df.corr() method of was used, and the results were visualized using seaborn’s heatmap, presented next.

Figure 7: Correlation matrix of the dataset

Interpreting this heatmap highlights the strong correlation between the X-coordinate and the corresponding maintenance step. It also shows that despite the Y and Z coordinates showing a weaker correlation with the target, none of the features demonstrate strong correlation with each other, implying that they are linearly independent. As such, no features will be dropped from the training data, in order to provide the model with more information to make predictions.

**Data Preparation**

As mentioned previously, the data will need to be scaled before it can be used to train a model. The two most common methods for data scaling are standardization, or normalization. Standardization is typically used when the data exhibits a gaussian, or bell-shaped distribution. From figures 5, 7, and 9, it is evident that only the Z-coordinates exhibit this behavior. For simplicity, a min/max scaler was used for all 3 features. The decision to scale the features differently could be a potential hyperparameter for further model tuning, but will not be explored in this project.

**Model Selection and Tuning**

The following section details the selection and tuning of 5 machine learning models from the scikit-learn library. The first 3 were developed using grid search cross-validation, one utilized random search cross-validation, and the final model is a stacked classifier using logistic regression as the final estimator.

The first model chosen was a random forest classifier. This model was chosen for its native ability to handle multiclass classification problems such as this one. The parameters used were n\_estimators, max\_depth, min\_samples\_split, and\_min\_samples\_leaf. The range of values were adjusted until the best parameters lay somewhere in the middle of the given range, indicating that the range of optimal parameters had been found. This method was used for the other 2 models trained using grid search. For each model, 5 folds were utilized.

It is important to note that of all of the models trained, the random forest took by far the most time every time it was fit. The biggest influence seemed to be the n\_estimators parameter, where higher values led to longer runtimes.

The next model selected was a support vector classifier. In contrast to the random forest classifier, a support vector classifier is just a binary classifier, and to handle a multiclass problem, it essentially trains multiple binary classifiers using a one vs rest scheme. The hyperparameters used in this model were C, kernel, and gamma. In contrast to the random forest, this model only took a few seconds to train.

The last model trained was

Data Visualization

* Generate a boxplot for the data, per class
* Include count of step per class
  + Discuss maintaining distribution of classes for train and test set
* Include range of each coordinate per class
  + Discuss differing ranges for each feature, and the need for scaling
  + Discuss decision to use min/max scaling instead of standard

Correlation Analysis

* Include correlation heatmap
* Discuss low correlation between features
  + All features are highly independent, at least linearly
* Discuss high correlation with x-coordinate and step
* Discuss low correlation of z-axis and class
  + Could potentially be removed without significant impact on model
  + Makes sense physically, as humans down really translate about this axis, at least macroscopically

Data preparation

* Discuss min/max scaling decision

Model Development

* Discuss choice of classifiers
  + Some that can handle native multiclassification natively
  + Include sklearn decision flowchart
* General for each model
  + Discuss choice of parameters in parameter grid
  + Discuss using multi-scoring instead of just accuracy
  + Discuss process of tuning with GridSearch
    - Tweaking values until best parameters fall within range, ensuring model isn’t limited by range of chosen hyperparameters
* Random forest
  + Able to handle multiclass tasks natively
* Complement Naïve Bayes
  + Good for imbalanced datasets
  + Default values are even worse in terms of accuracy
  + Fit is almost instantaneous compared to other models
* SVM
  + Recommended by sklearn
* Gaussian naïve bayes
  + CNB had really poor performance
  + Want to compare to the base classifier

Model Analysis

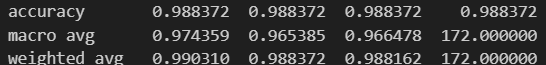
* Generate scoring reports for each model
  + Test and train sets
    - Discuss if overfitting seems to be an issue
* Discuss scoring metrics
  + Meaning of each in context of problem
  + Which ones to favour
  + Why not recall
  + Weighted average
* Select best model
  + Generate confusion matrix for it
  + Discuss confusion matrix results
  + Discuss errors with the model
  + Evaluate on test set

Stacked Model

* Combine two models and evaluate performance
* Combined best performing models
* Slight higher accuracy from stacked model

Model Evaluation

Random Forest



SVC

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Description générée automatiquement

CNB

Une image contenant texte, Police, capture d’écran, noir

Description générée automatiquement

GNB

Une image contenant texte, Police, capture d’écran, noir

Description générée automatiquement

Stacked

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Description générée automatiquement

Joblib